

1. Let

$$R(t) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos t & -\sin t \\ 0 & \sin t & \cos t \end{pmatrix}$$

$R(t)$  is an orthogonal matrix. It preserves the lengths of vectors in  $\mathbb{R}^3$  and so induces a map  $R(t) : S^2 \rightarrow S^2$  on the two-dimensional unit sphere. For  $p \in S^2$  the smooth curve,

$$t \mapsto c_p(t) = R(t)p = R(t) \begin{pmatrix} p^1 \\ p^2 \\ p^3 \end{pmatrix} \in S^2$$

goes through  $p$  at  $t = 0$  and so defines a tangent vector  $V_p = c'_p(0) \in T_p S^2$ . Find the coordinate representation for this tangent vector in the  $u$  coordinates of stereographic projection from the north pole. Recall that:

$$u(p) = \frac{(p^1, p^2)}{1 - p^3}$$

and

$$p = \left( \frac{2u}{|u|^2 + 1}, \frac{|u|^2 - 1}{|u|^2 + 1} \right), \text{ where } u = (u^1, u^2).$$

That is find  $f^j(u)$  for  $j = 1, 2$  so that,

$$u_{*p}(V_p) = f^1(u) \frac{\partial}{\partial u^1} + f^2(u) \frac{\partial}{\partial u^2}$$

**Solution.** Consider  $R$  acting on  $p$  coordinate-wise and represent this action by  $p^i \mapsto Rp^i$ . To represent this tangent vector at  $t = 0$ , consider the following for the first coordinate

$$\begin{aligned} \left. \frac{d}{dt} \left( \frac{Rp^1}{1 - Rp^3} \right) \right|_{t=0} &= \left. \frac{(Rp^1)'(1 - Rp^3) - (1 - Rp^3)'Rp^1}{(1 - Rp^3)^2} \right|_{t=0} \\ &= \left. \frac{(p^2 \cos t - p^3 \sin t)p^1}{(1 - (p^2 \sin t + p^3 \cos t))^2} \right|_{t=0} \\ &= \frac{-p^1 p^2}{(1 - p^3)^2} \end{aligned}$$

and in the second coordinate

$$\begin{aligned}
\left. \frac{d}{dt} \left( \frac{Rp^2}{1 - Rp^3} \right) \right|_{t=0} &= \left. \frac{(Rp^2)'(1 - Rp^3) - (1 - Rp^3)'Rp^2}{(1 - Rp^3)^2} \right|_{t=0} \\
&= \left. \frac{(-p^2 \sin t - p^3 \cos t)(1 - (p^2 \sin t + p^3 \cos t)) + (p^2 \cos t - p^3 \sin t)^2}{(1 - (p^2 \sin t + p^3 \cos t))^2} \right|_{t=0} \\
&= \frac{-p^3(1 - p^3) + (p^2)^2}{(1 - p^3)^2}.
\end{aligned}$$

So, we have the following in terms of  $u(p)$ ,

$$\begin{aligned}
f^1(u(p)) &= \frac{-p^1 p^2}{(1 - p^3)^2} \\
f^2(u(p)) &= \frac{-p^3(1 - p^3) + (p^2)^2}{(1 - p^3)^2}.
\end{aligned}$$

Now apply the coordinate transformation for stereographic projection from the north pole to get

$$\begin{aligned}
f^1(u) &= \frac{\frac{-4u^1 u^2}{(|u|^2+1)^2}}{\left(1 - \frac{|u|^2-1}{|u|^2+1}\right)^2} \\
&= \frac{-4u^1 u^2}{(|u|^2 + 1 - (|u|^2 - 1))^2} \\
&= -u^1 u^2 \\
f^2(u) &= \frac{\left(\frac{1-|u|^2}{|u|^2+1}\right)\left(1 - \frac{|u|^2-1}{|u|^2+1}\right) + \left(\frac{2u_2}{|u|^2+1}\right)^2}{\left(1 - \frac{|u|^2-1}{|u|^2+1}\right)^2} \\
&= \frac{(1 - |u|^2)(|u|^2 + 1 - (|u|^2 - 1)) + 4(u^2)^2}{(|u|^2 + 1 - (|u|^2 - 1))^2} \\
&= \frac{2(1 - |u|^2) + 4(u^2)^2}{4} \\
&= \frac{1}{2}(1 - |u|^2) + (u^2)^2
\end{aligned}$$

Therefore, we have the coordinate representation for  $V_p \in T_p S^2$ ,

$$\begin{aligned}
u_{*p}(V_p) &= f^1(u) \frac{\partial}{\partial u^1} + f^2(u) \frac{\partial}{\partial u^2} \\
&= -u^1 u^2 \frac{\partial}{\partial u^1} + \frac{1}{2}(1 - |u|^2) + (u^2)^2 \frac{\partial}{\partial u^2}
\end{aligned}$$

□

2. Suppose that  $g : \mathbb{R}^n \rightarrow \mathbb{R}$  is a smooth function and 0 is a regular value so that  $M = g^{-1}(0)$  is a regular submanifold. Suppose that  $U$  is an open neighborhood of  $M$  in  $\mathbb{R}^n$  and  $F : U \rightarrow \mathbb{R}$  is a smooth function on  $U$ , and write  $f = F|_M$  for the restriction of  $F$  to  $M$ . Show that for  $p \in M$ ,

$$F_{*,p}(v) = f_{*,p}(v) \text{ for } v \in T_p M$$

Use this to show that  $p$  is a critical point for  $f$  on  $M$  if and only if there exists a constant  $\lambda$  so that,

$$F_{*,p} = \lambda g_{*,p}$$

The constant  $\lambda$  is called a Lagrange multiplier. Use this to find the critical points for the restriction of the function  $F(x, y, z) = xy$  to the unit sphere,  $g(x, y, z) = x^2 + y^2 + z^2 - 1 = 0$ . Hint: a linear functional on a finite dimensional vector space is determined up to a constant multiple by its null space.

**Solution.** Represent  $v$  by the derivative of the germ of a  $C_p^\infty(\mathbb{R})$  function evaluated at  $t = 0$ ; call it  $c(t) : \mathbb{R} \rightarrow \mathbb{R}$ . Therefore  $v = c'(0)$ , and hence it follows that

$$\begin{aligned} F_{*p}(v) &= F_{*p}(c'(0)) \\ &= f_{*p}(c'(0)) \\ &= f_{*p}(v) \end{aligned}$$

□

Now, consider  $M = g^{-1}(0)$ . It follows that  $M$  is a level set for  $g$  and that, for any  $c \in C_p^\infty(\mathbb{R})$ ,  $g \circ c(t)$  is constant for all  $t \in \mathbb{R}$ . Therefore,  $\frac{d}{dt}(g \circ c(t)) = 0$  for all  $t$ . This implies that  $\text{rk}(g_{*p}) = 1$  and  $\dim(N(g_{*p})) = n - 1$ , for  $M$   $n$ -dimensional. Now consider  $f_{*,p}$  when  $p$  is critical. Then

$$f_{*p} = 0 = F_{*p}$$

Now, because  $F_{*p} = 0$ ,  $\dim(N(F_{*p})) = \dim(N(g_{*p})) = n - 1$ . We can apply the hint given in the problem statement to conclude

$$F_{*p} = \lambda g_{*p}$$

for some  $\lambda \in \mathbb{R}$  when  $p$  is critical.

The notion of  $p$  being a critical point is crucial. If  $p$  were a regular point, then  $F_{*p} \neq 0$ . From the argument above,  $g_{*p} = 0$ , and so there could not exist a constant  $\lambda$  s.t.  $F_{*p} = \lambda g_{*p}$ . So, if  $F_{*p} = \lambda g_{*p}$ ,  $p$  must be a critical point.

Therefore,  $p$  is a critical point for  $f$  on  $M$  if and only if there exists a constant  $\lambda$  so that,

$$F_{*,p} = \lambda g_{*,p}$$

□

We can use the above construction to find the critical points of  $F(x, y, z) = xy$  restricted to the unit sphere  $g(x, y, z) = x^2 + y^2 + z^2 - 1 = 0$ . Notice  $S^2 = g^{-1}(\{0\})$ . Calculate the derivations at  $p$ ,

$$\begin{aligned} g_{*p} &= 2xdx_p + 2ydy_p + 2zdz_p \\ F_{*p} &= ydx_p + xdy_p. \end{aligned}$$

We are looking for points at which

$$F_{*p} = \lambda g_{*p}$$

which would imply

$$ydx_p + xdy_p = \lambda(2xdx_p + 2ydy_p + 2zdz_p).$$

Clearly,  $z$  must be 0 for equality to hold. Additionally,  $x = \pm y$  to ensure proper cancellation. This then shows that  $\lambda = \pm \frac{1}{2}$ . Therefore, the critical points on  $S^2$  are  $(\pm \frac{1}{\sqrt{2}}, \pm \frac{1}{\sqrt{2}}, 0)$ .  $\square$

3. Show that  $-1$  is a regular value for the function,

$$F(x, y, z) = z^2 - x^2 - y^2$$

So that  $M = F^{-1}(-1)$  is a regular submanifold of  $\mathbb{R}^3$ . Show that the map,

$$S^1 \times \mathbb{R} \ni (p, z) \rightarrow \phi(p, z) = (\sqrt{z^2 + 1}p, z) \in M$$

is a diffeomorphism of  $S^1 \times \mathbb{R}$  with  $M$ .

**Solution.** Consider the partial derivatives

$$\frac{\partial F}{\partial x} = -2x, \quad \frac{\partial F}{\partial y} = -2y, \quad \frac{\partial F}{\partial z} = 2z.$$

These partials all vanish at  $(0, 0, 0)$  only and  $(0, 0, 0) \notin F^{-1}(\{-1\})$ . So, we can conclude that  $-1$  is a regular value for  $F$ .  $\square$

To show that  $\phi$  as defined is a diffeomorphism, it must be a bijection,  $C^\infty$ , and have a  $C^\infty$  inverse. To show that  $\phi$  is a bijection, it is sufficient to show that  $\phi^{-1} : M \rightarrow S^1 \times \mathbb{R}$  is a function. Observe that

$$\phi^{-1}(x, y, z) = \left( \frac{x}{\sqrt{z^2 + 1}}, \frac{y}{\sqrt{z^2 + 1}}, z \right).$$

This map is a function since each point in the domain  $M$  maps to a single point in  $S^1 \times \mathbb{R}$ . By inspection,  $\phi$  is  $C^\infty$  since there is no problem with partial differentiation being infinite in any of the coordinates. Now, to see if  $\phi^{-1}$  is  $C^\infty$ , check the determinant of the Jacobian matrix

$$\det D\phi = \begin{vmatrix} \sqrt{z^2 + 1} & 0 & \frac{xz}{\sqrt{z^2 + 1}} \\ 0 & \sqrt{z^2 + 1} & \frac{yz}{\sqrt{z^2 + 1}} \\ 0 & 0 & 1 \end{vmatrix} = z^2 + 1$$

Since this determinant is non-zero everywhere,  $\phi$  is locally invertible everywhere on  $S^1 \times \mathbb{R}$  by the Inverse Function Thm. It follows that  $\phi^{-1}$  is  $C^\infty$ . So,  $\phi$  is diffeomorphism.  $\square$